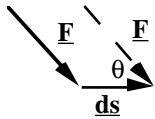


Work and Energy



When force varies, use differential displacement ds

$$dW \equiv F ds \cos \theta$$

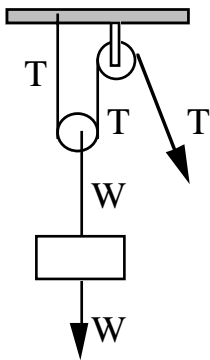
ds X component of F // ds
or

F X component of ds // F

$$W = \int_0^L F \cos \theta ds$$

if F is constant, we get $W = FL \cos \theta$

SI Unit: 1 Newton x 1 metre = 1 Joule



If the rope and pulleys are light, and if the accelerations are negligible, then

Force on LH pulley

$$ma \cong 0 = 2T - W$$

$$\therefore T = W/2$$

If mass rises by D , work done = WD .

But rope shortens on both sides of rising pulley,

if mass rises by D , rope must be pulled $2D$, so work done = $T \times 2D = WD$

Example. $F_{\text{grav}} \propto 1/r^2$. How much work is done to move $m = 1$ tonne from earth's surface ($r = 6500$ km) to $r = \infty$?

$$W = \int F ds \cos \theta$$

$$= \int F dr$$

$$F = -F_{\text{grav}} = \frac{Cm}{r^2}$$

On surface $F/m = 9.8 \text{ ms}^{-2}$

$$\therefore C = (9.8 \text{ ms}^{-2})(6.5 \cdot 10^6 \text{ m})^2 = 4.1 \cdot 10^{14} \text{ m}^3\text{s}^{-2}$$

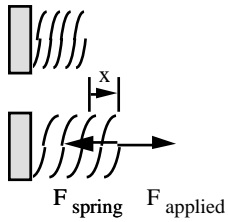
$$W = \int_{6500 \text{ km}}^{\infty} \frac{Cm}{r^2} dr$$

$$= -Cm \left(\frac{1}{\infty} - \frac{1}{6.5 \cdot 10^6} \right)$$

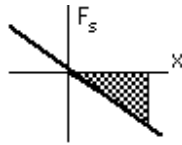
=

$$= 6.3 \cdot 10^{10} \text{ J} = 63 \text{ GJ.}$$

Work to deform spring



No applied force
($x = 0$)

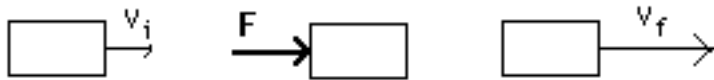


$$\begin{aligned}\text{Work done by spring} &= \int F_{\text{spring}}.dx \\ &= \int -kx.dx = -\frac{1}{2}kx^2\end{aligned}$$

$$\begin{aligned}\text{Work done on spring} &= \int F_{\text{applied}}.dx \\ &= \int kx.dx = +\frac{1}{2}kx^2\end{aligned}$$

Work and kinetic energy

(Total) force F acts on mass m in x direction.



$$\begin{aligned}\text{Work done by } F &= \int_i^f F dx \quad (\text{use } F = ma) \\ &= \int_i^f m \frac{dv}{dt} dx = \int_i^f m \frac{dx}{dt} dv \\ &= \int_i^f mv.dv\end{aligned}$$

$$\text{Work done by } F = \frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2$$

$$\text{Define kinetic energy } K \equiv \frac{1}{2}mv^2$$

Increase in kinetic energy of body = work done by **total** force acting on it.

Power. Rate of doing work

$$\text{Average power} \quad \bar{P} \equiv \frac{W}{\Delta t}$$

$$\text{Instantaneous power} \quad P = \frac{dW}{dt}$$

SI unit: 1 Joule per second \equiv 1 Watt (1 W)

*(humans can produce 100s of W,
car engines several tens of kW)*

Potential energy.

e.g. Compress **spring**, do W on it, but get no K . Yet can get energy out: spring can expand and give K to a mass. \rightarrow Idea of stored energy.

e.g. **Gravity**: lift object (slowly), do work but get no K . Yet object can fall back down and get K .

But: Slide mass slowly along a surface. Do work against **friction**, but can't recover this energy mechanically. Not all forces "store" energy

Conservative and non-conservative forces

$$\begin{aligned}
 W_{\text{against grav}} &= - \int_i^f F_g dr \cos \theta \\
 &= - \int_i^f F_g dz \\
 &= mg \int_i^f dz \\
 &= mg (z_f - z_i) \quad \text{in uniform field}
 \end{aligned}$$

W is uniquely defined at all \underline{r} , i.e. $W = W(\underline{r})$

If $z_f - z_i$ are the same, $W = 0$.

\therefore Work done against gravity round a closed path = 0

Gravity is a **conservative force**

$$\begin{aligned}
 W_{\text{against spring}} &= - \int_i^f F_{\text{spring}} dx \\
 &= - \int_i^f -kx dx = \frac{1}{2} k(x_f^2 - x_i^2)
 \end{aligned}$$

W is uniquely defined at all x, i.e. $W = W(x)$

$x_f = x_i \Rightarrow W = 0$.

\therefore Work done round a closed path = 0

Spring force is a **conservative force**

Friction

$$dW_{\text{against fric}} = - F_f ds \cos \theta$$

but F_f always has a component *opposite* ds

$\therefore dW$ always ≥ 0 . *(we never get work back)*

\therefore cannot be zero round closed path, $\therefore W \neq W(\underline{r})$

\therefore friction is a **non-conservative force**

Potential energy

For a **conservative** force \underline{F} (i.e. one where work done against it, $W = W(\underline{r})$) we can define potential energy U by

$\Delta U = W_{\text{against}}$. i.e.

$$\Delta U = - \int_i^f \underline{F} \cdot d\underline{r} \cos \theta$$

Same examples: **spring**

$$\Delta U_{\text{spring}} = - \int_i^f F_{\text{spring}} dx = \frac{1}{2} k(x_f^2 - x_i^2)$$

Choice of zero for U is arbitrary.

Here $U = 0$ at $x = 0$ is obvious, so $U_{\text{spring}} = \frac{1}{2} kx^2$

From energy to force:

$U = - \int F \, ds$ where ds is in the direction // F

$$F = - \frac{dU}{ds}$$

$$\text{in fact } F_x = - \frac{dU}{dx}, F_y = - \frac{dU}{dy}, F_z = - \frac{dU}{dz}$$

Spring: $U_{\text{spring}} = \frac{1}{2} kx^2 \quad \therefore F_{\text{spring}} = - kx$

Gravity: $U_g = mgz \quad \therefore F_g = - \frac{dU}{dz} = - mg$

Energy of interaction:

Conservation of mechanical energy

Recall: Increase in K of body = work done by **total** force acting on it. *(restatement of Newton 2)*

But, if all forces are conservative, work done **by** these forces

$$= - \Delta U \quad (\text{definition of } U)$$

$$\therefore \text{ if only conservative forces act, } \Delta K = - \Delta U$$

We define mechanical energy

$$E \equiv K + U$$

so, if only conservative forces act, $\Delta E = 0$.

we can make this stronger.

Work done by **non-conservative forces**

Define internal energy U_{int} where

$$\Delta U_{\text{int}} = - \text{Work done by n-c forces} \\ (= + \text{Work done against n-c forces})$$

Recall defⁿ of K : $\Delta K = \text{work done by } \Sigma \text{ force}$

$$\therefore \Delta K = - \Delta U - \Delta U_{\text{int}}$$

$$\therefore \Delta K + \Delta U + \Delta U_{\text{int}} = 0$$

If n-c forces do no work, then $\Delta U_{\text{int}} = 0$, so:

If non-conservative forces do no work,

$$\Delta E = \Delta K + \Delta U = 0$$

or: **mechanical energy is conserved**

Never, ever write: *"kinetic energy = potential energy"*

Example. Freda ($m = 60 \text{ kg}$) rides pogo stick ($m \ll 60 \text{ kg}$) with spring constant $k = 100 \text{ kN.m}^{-1}$. Neglecting friction, how far does spring compress if jumps are 50 cm high?

Non-conservative forces do no work, \therefore mechanical energy is conserved, i.e.

$$E_{\text{bottom}} = E_{\text{top}}$$

$$K_b + U_b = K_t + U_t \quad (U = U_{\text{grav}} + U_{\text{spring}})$$

$$\frac{1}{2} m v_{\text{horiz}}^2 + (mgy_b + \frac{1}{2} kx_b^2) \equiv \frac{1}{2} m v_{\text{horiz}}^2 + (mgy_t + \frac{1}{2} kx_t^2)$$

$$mg(y_t - y_b) \equiv \frac{1}{2} kx_b^2$$

$$\therefore x_b \equiv \sqrt{\frac{2mg(y_t - y_b)}{k}} \equiv 80 \text{ mm.}$$